



# Exercise

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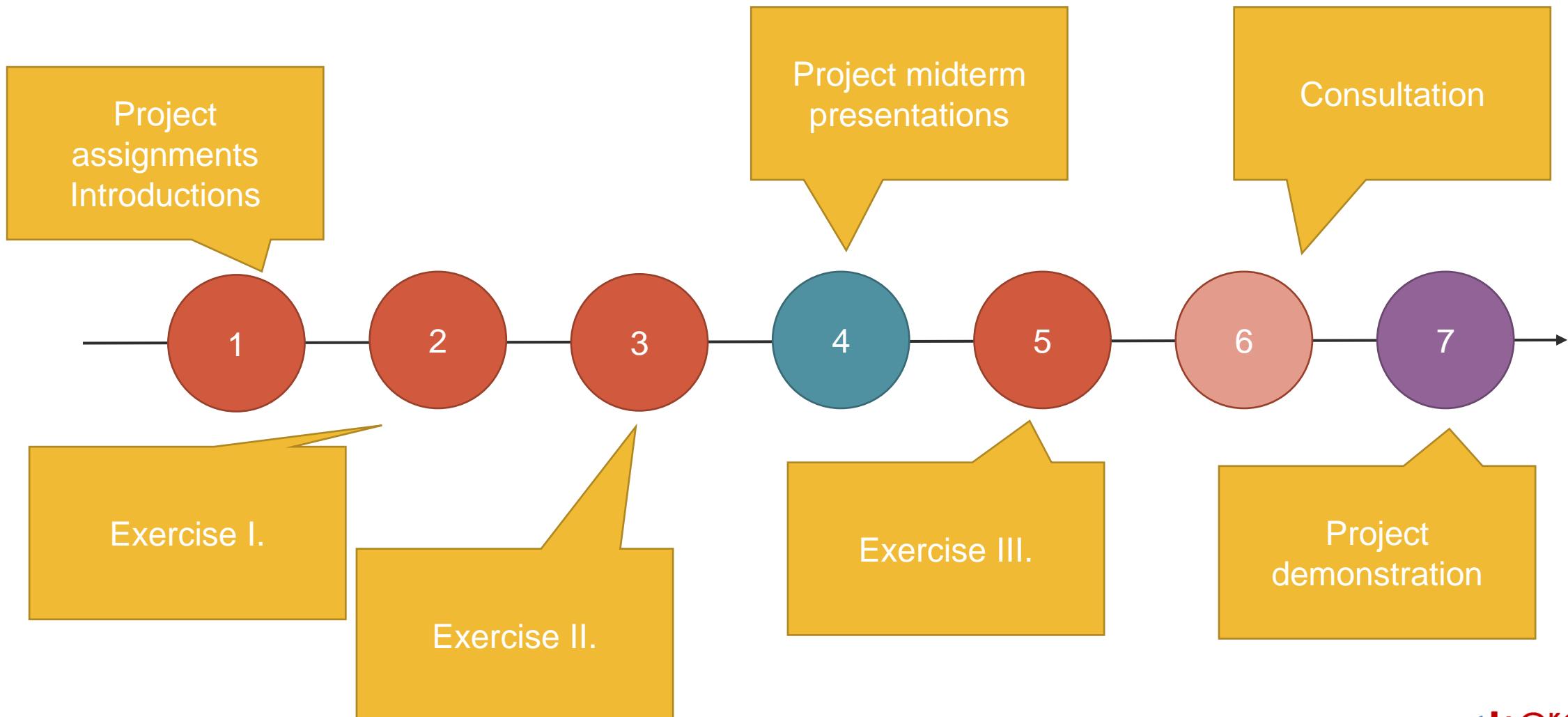
VITMMA09 – SmartCity MSc specialization

# SmartCity exercise

- Targets
  - Hands on experiences to extend theoretical studies
  - Real world examples in a small but realistic environment
    - Design, implementation, test
  - Useful knowledge
- Method
  - Project work with small groups (3-4 students/group)
  - Homework projects with demonstrations
    - Exercises for preparations, but additional studies also required
    - Consultations
- Exercises at the University
  - **Participation is required for the signature! Min 70%**

# Project assignment, demonstrations

## ▪ Exercises

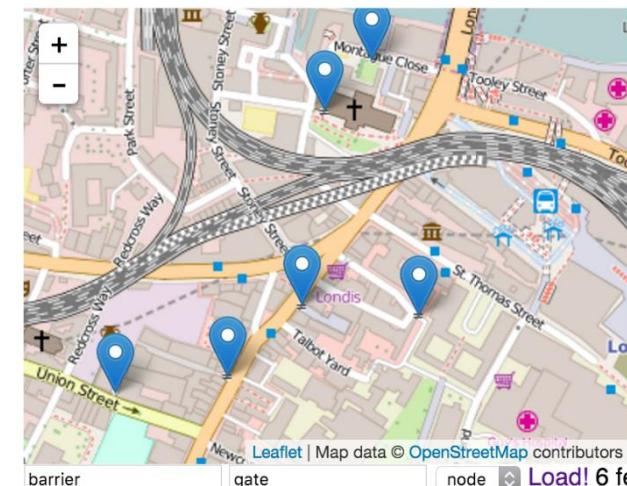


# Project environment

- Hardware work
  - Microcontrollers with communication
    - Arduino, Nucleo, ESP8266
    - WiFi, Bluetooth, CAN bus
  - Vehicles (toys)
    - Cars, drone



- Software work
  - Android apps
    - Android Studio
  - Web apps
    - Javascript, python, PHP
    - Web APIs
  - Simulation frameworks



# Projects

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# Project type A. – CAN bus

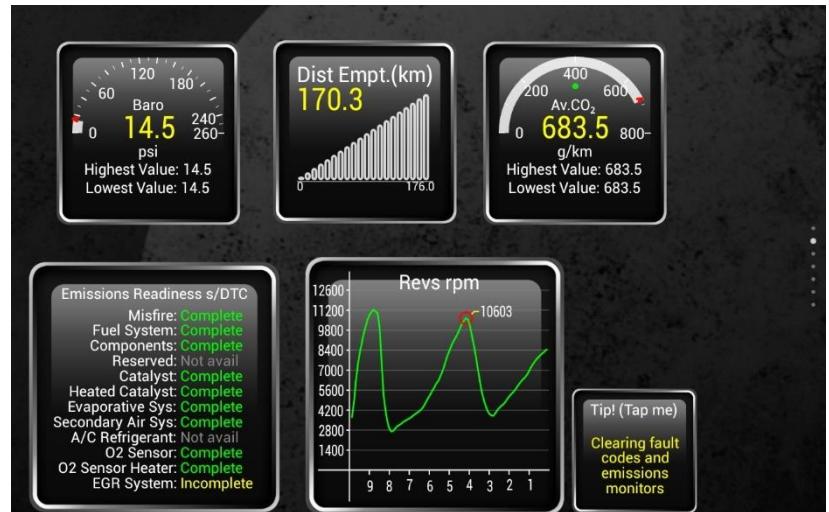
- CAN bus communication
  - Device to device communication
    - Standard and fault tolerant CAN
  - Controlling real instrument clusters
  - Car hacking



- OnBoardDiagnostics (OBD)
  - Communication, apps

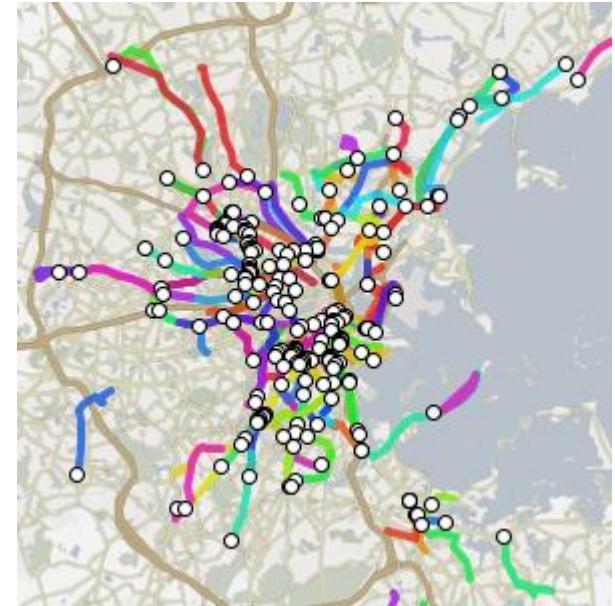


- Max. 2 projects



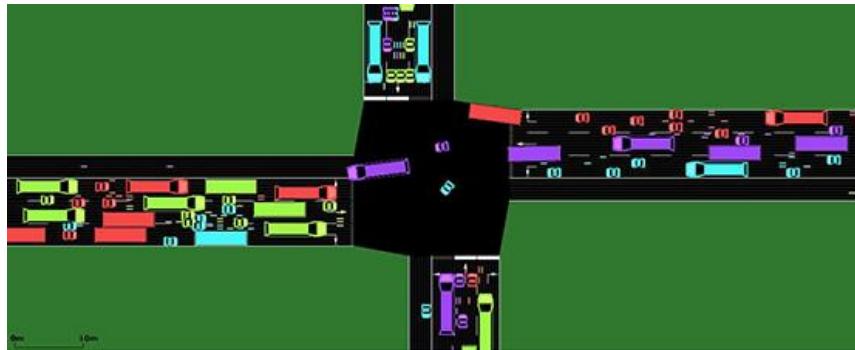
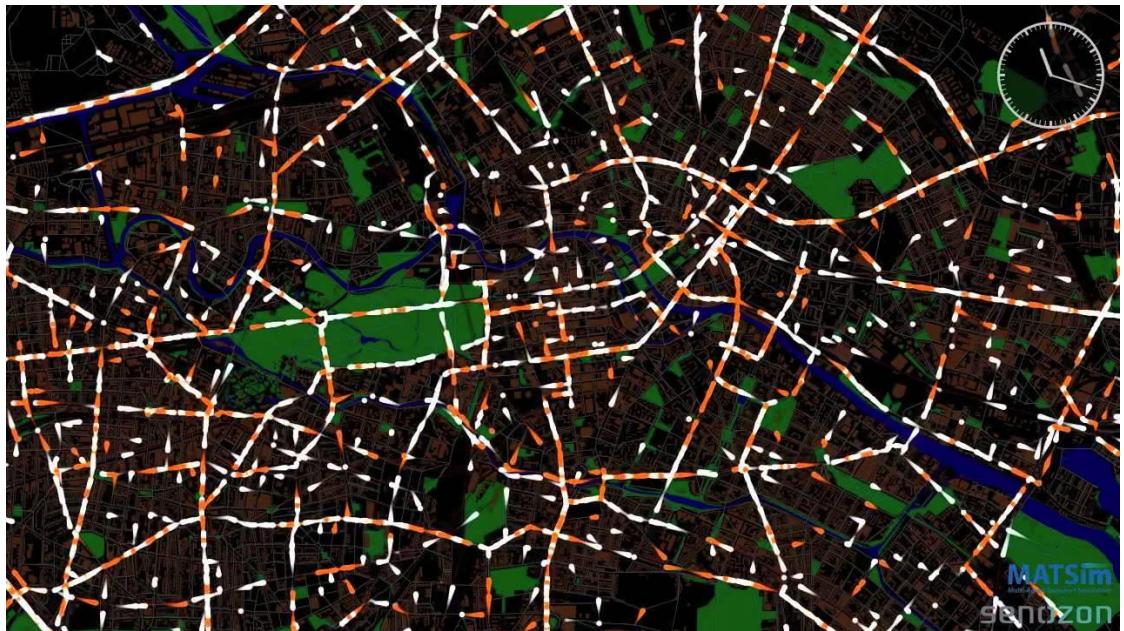
# Project type B. – Mapping

- Map based apps and services
  - Route planning, rendezvous, mass transportation, info display, parking, ...
- Open Street Maps, Google maps
- General Transit Feed Specification (GTFS)
  - Live feeds, schedule
- Routing
  - Google, others...
- Mobile apps
  - Crowdsensing, crowdsourcing
  - Social apps based on mobile phone sensors, movement predictions, GPS, communications
  - Social apps based on route planning
- Max. 3 projects



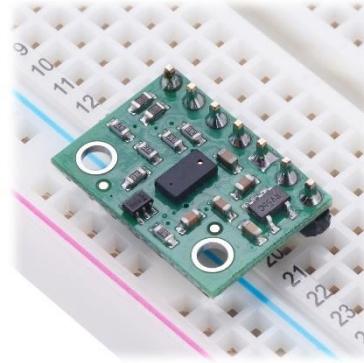
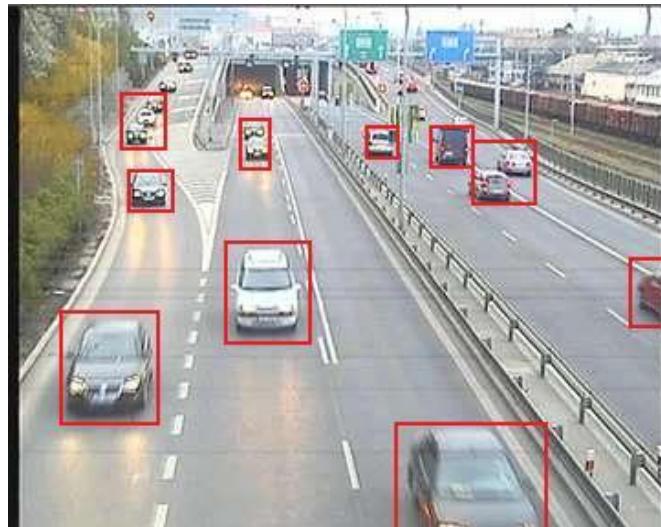
# Project type C – Traffic simulation

- Traffic simulation
  - Parking, Traffic jams, Mass transportation
  - Simulating events based on real data
- GTFS integration
- OSM integration
- Simulation tools
  - Multi-Agent Transport Simulation – MATSIM
  - Simulation of Urban MObility – SUMO
- Max. 1 project



# Project D. – Autonomous Driving (kindof)

- Sensors
  - Distance sensors
    - LIDAR (Light Detection and Ranging)
    - Ultrasonic distance sensor
    - Proximity sensor / bumper
  - Camera
    - Raspberry Pi cameras
- Computer vision
  - OpenCV
- Vehicles
  - Parrot Air.Drone 2.0
  - RC cars
  - Cleaner robot
- Max. 2 projects



# Project X. – Your idea

- Tell us your idea!

# Skills required

- Project A.
  - Electrical: proto boards, soldering, handling oscilloscope
  - Knowledge: CAN bus theory, signals
  - Reverse engineering: Instrument clusters, BMW, Mazda protocols,
  - Programming: embedded coding, visualization
- Project B.
  - Knowledge: GTFS format and related protocols
  - Programming: APIs
- Project C.
  - Knowledge: GTFS format and related protocols
  - Programming: Simulators in C++, C, Java, ...
- Project D.
  - Electrical: proto boards, soldering, handling oscilloscope
  - Knowledge: Control protocols, APIs, computer vision
  - Programming: embedded coding, OpenCV, AI