



C-V2x Intelligent Transportation Systems

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IEEE 1609.x

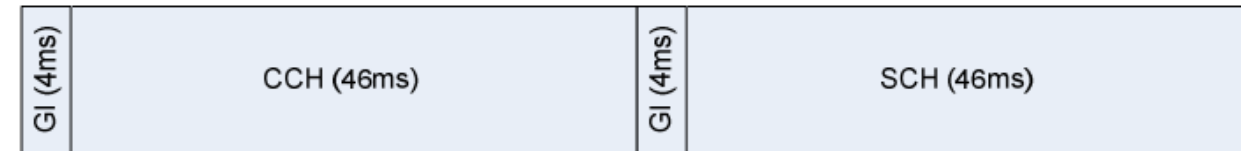
- IEEE 1609.2 – security services
- IEEE 1609.3 – management services
 - Channel usage monitoring
 - Received channel power indicator (RCPI)
 - Management parameters
- IEEE 1609.4 – QoS and multi-channel access
 - User Priorities mapped to Access Categories in EDCA
 - Multi-channel access for single radio 802.11p devices



IEEE 1609.4 channel swithcing

- 7 FDMA channel frequencies
- **Multi-channel radios** can send and receive over several channels simultaneously
 - Might have problems with interferences between channels
- **Single channel radios** to access both CCH and SCH
 - Either transmit or receive on a single 10 MHz channel

- **Alternating access**



- Repetitive periods of 100 ms
 - 46 ms allocated to the CCH channel
 - 46 ms allocated to the SCH channels
 - 4 ms guard interval for switching between CCH and SCH
 - Nodes should wait for a random backoff after the end of the guard interval, before starting to transmit
- Time synchronisation needed to an external time reference
 - Coordinated Universal Time (UTC) from GPS or other devices
 - **WAVE Time Advertisement (WTA)** frame

IEEE 1609.4 channel switching

- **Continuous access**
 - Transmission can be continuous on the CCH and all SCHs
 - It cannot be guaranteed that all other stations will listen to the CCH outside the CCH slot
 - Safety messages sent over the CCH in the SCH slot might be ineffective
 - The usage of SCH not efficient if nodes listen to the CCH 50% of the time

- Alternative solutions to minimise the impact of channel switching?

IEEE 1609.4 channel switching

▪ Immediate access

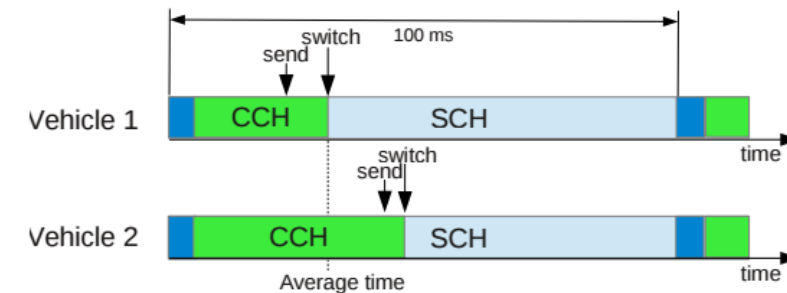
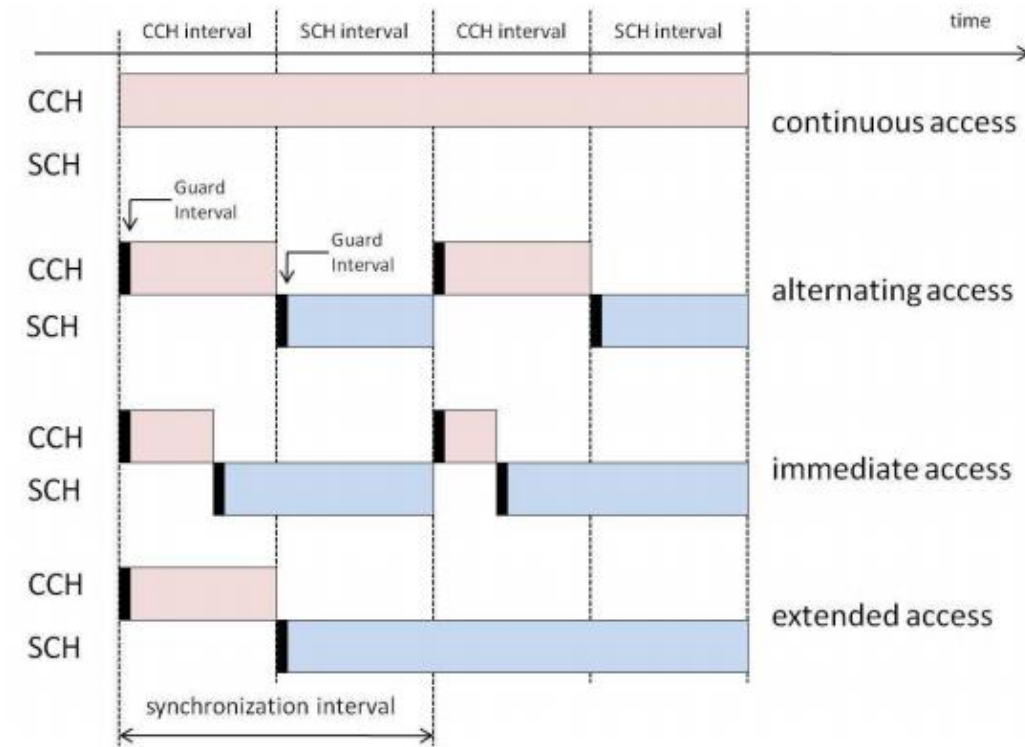
- The node does not have to wait until the CCH slot is over
- After the CCH transmission is over, switch to SCH
- Improve the performance of bandwidth-demanding non-safety applications in SCH, at the expense of the CCH

▪ Extended access

- Transmission on the SCH without waiting for the CCH

▪ Adaptive Independent Channel Switching

- If more vehicles, more beacons on the CCH
- Nodes can change their average switching time based on vehicle density
 - Long SCH intervals if not many vehicles
 - Fewer collisions at the start of the SCH, as nodes switch independently of each other
- Drawback is that not all nodes on the CCH in the same time
 - Vehicle 1 will miss the beacon of Vehicle 2



IEEE 1609.4 channel switching

▪ Fragmentation

- To better utilise the residual time at the end of the SCH interval
- An extra fragmentation header should be used, which is a drawback
- Works for large packets (TCP)

▪ Best-fit scheme

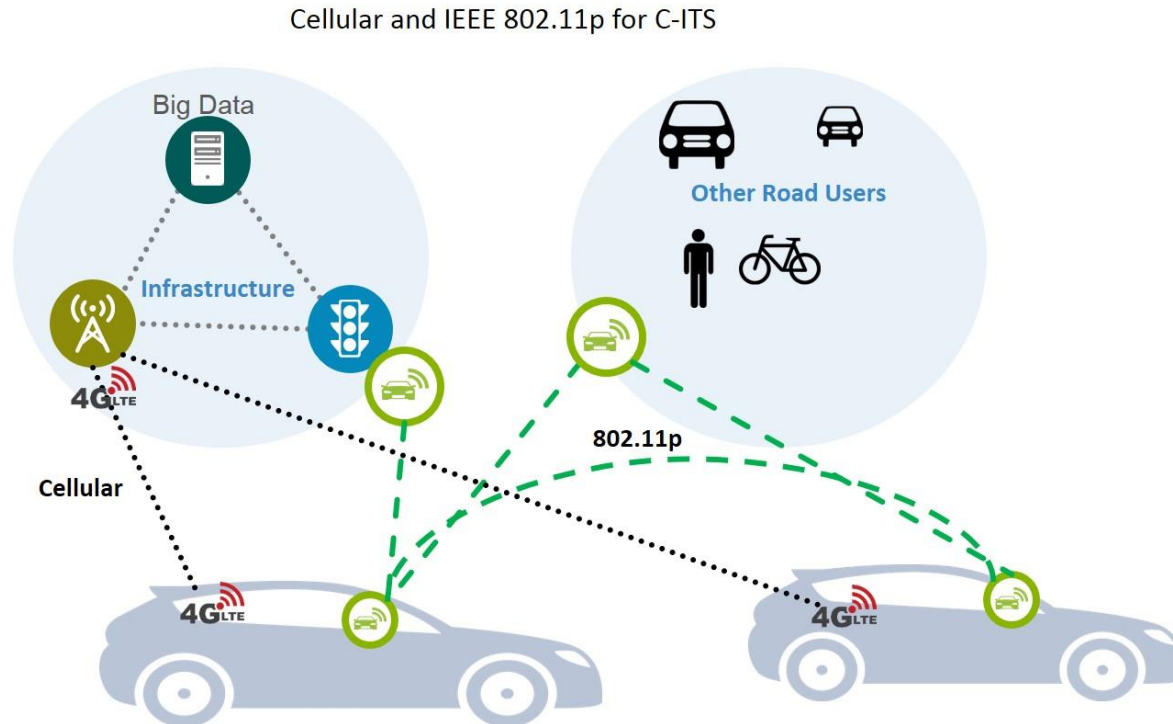
- Send the packet that best fits the residual time at the end of the SCH interval
 - Better than fragmentation only if packets of different sizes are present in the queue
- Hard to know in advance the actual duration of transmission
 - Frequent changes in the channel congestion
 - Stochastic nature of backoff

802.11p or C-V2x?

- Requirements for Cooperative ITS systems

- High relative speeds between transmitters and receivers
- Extremely low latency in safety-related applications (<50 ms)
- Tolerate high load generated by periodic transmission of multiple messages, and high vehicle density
- V2x messages are mostly local in nature, are important for nearby receivers

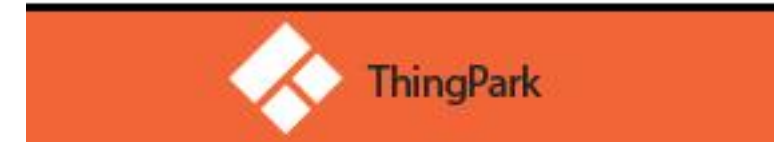
C-V2x: Cellular Vehicle to Everything



802.11p or C-V2x

- **802.11p is here today**
 - Standard approved in 2009
 - Several ETSI ITS plug-test events
 - Extensive field trials
 - Safety Pilot, Drive C2X, Score@F, simTD, etc.

- Significant efforts in the last 10 years to validate 802.11p
 - This should be re-done for any other alternative technology

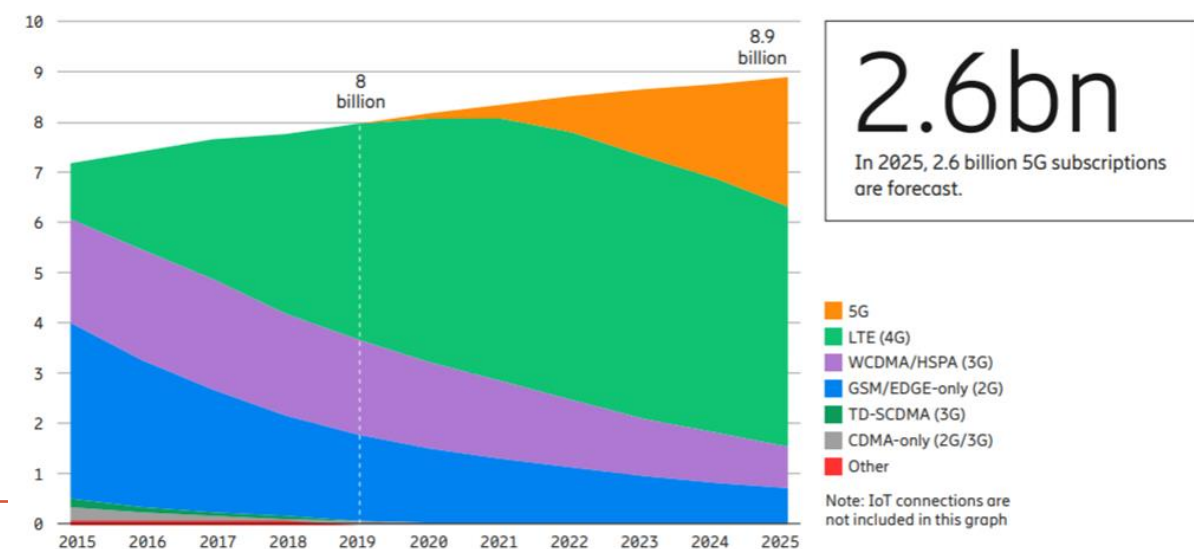


802.11p or C-V2x

- **Some argue that Cellular-V2x is still far out**
- Cellular technology is by far the most successful wireless standard
 - 5.5 billion mobile broadband subscriptions in Q2 2018
- LTE (Rel. 8) dates back to 2009, 5G unde deployment in 2020
 - Extensive cellular infrastructure, it takes time to upgrade
 - ~ 5 billion LTE subscribers still in 2025, next to 2.6 billion 5G subscribers
- LTE Rel. 8. can only address basic ITS use cases
 - No support for low latency and high mobility use cases
 - 3GPP V2x study group established in 2015

*Mobile subscriptions worldwide.
Source: Ericsson Mobility Report, November 2019*

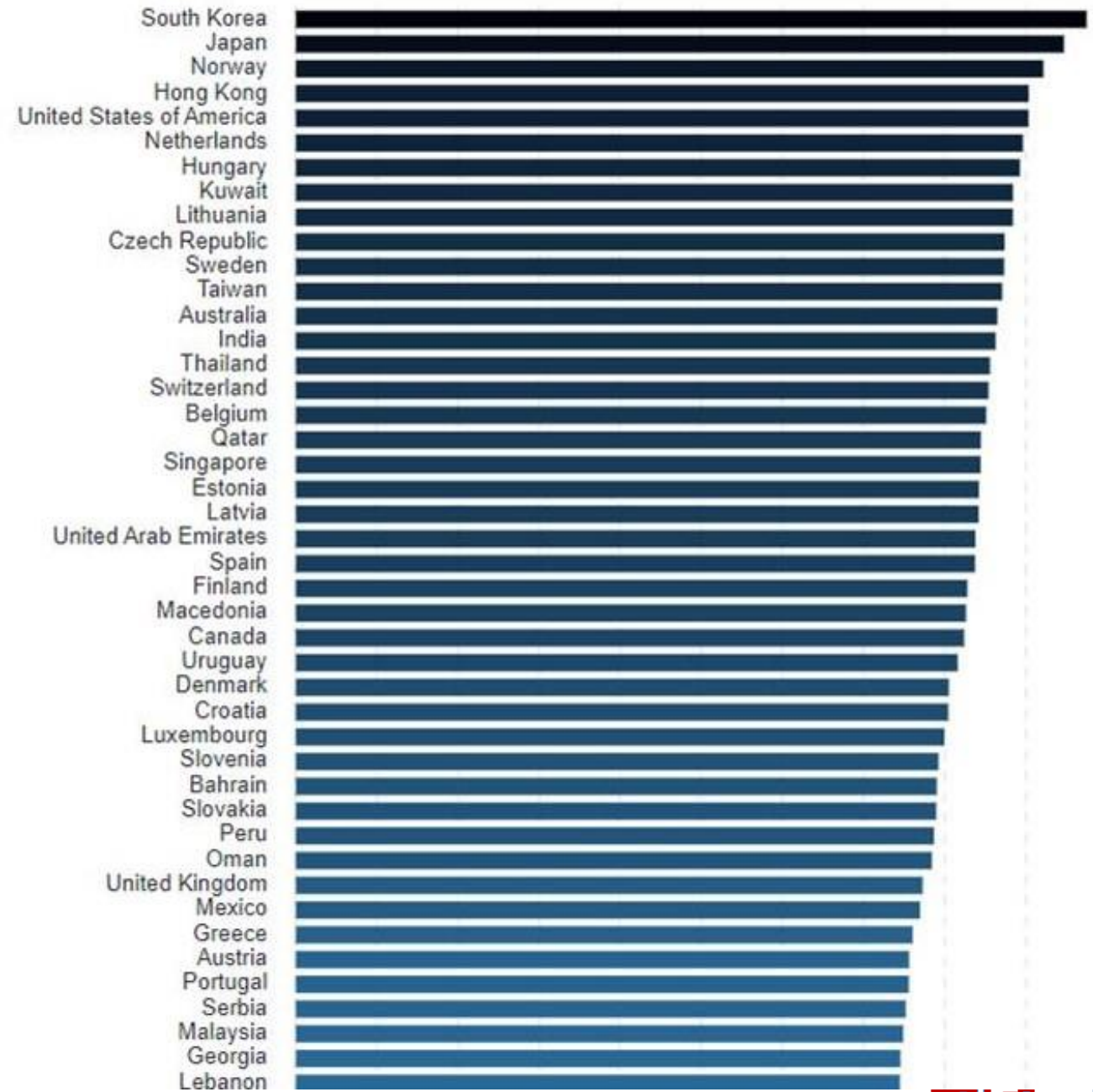
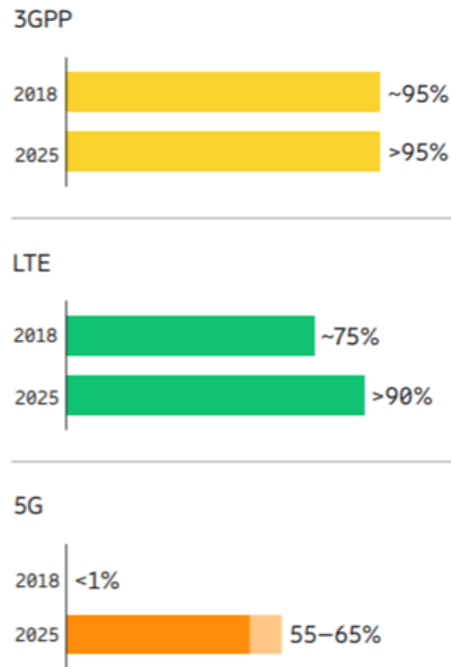
Figure 4: Mobile subscriptions by technology (billion)



State of LTE in 2018

- LTE coverage still far from 100%
 - Not geographic coverage, but percentage of time when LTE signal available to users
 - Around 65-68% in Germany, France
 - Extensive 3G infrastructure

Figure 15: World population coverage by technology²



LTE support for V2x applications

- LTE Release 8 can cover most of the V2I – I2V non-safety use cases
- Problem with very congested scenarios
 - evolved Multimedia Broadcast/Multicast Service (eMBMS) in LTE-A (Rel. 9)
 - Designed to support static scenarios – crowds in football stadiums
 - Not efficient when a large number of incoming and outgoing vehicles
- Problems with handovers between MNOs (mobile network operators) and cooperation between application service providers

LTE support for V2x applications

- Safety-related use cases represent the real challenge
 - Need complete coverage along the roads (which is not yet the case)
 - Need to handle high bandwidth with very low latency
- Some V2V use-cases require **continuous information exchange** (1 – 20 Hz)
 - **Cooperative Awareness Messages (CAM) - autonomous cars**
 - Too much data for LTE networks to handle
 - **Example: 256 bytes/message, 10 Hz, 2 hours of driving/day = 0.5 Gbyte per month per car**
 - **At the receiver side, assuming 30 cars in the area of interest, roughly 15 Gbytes per month**
 - 1 autonomous car in 2020 – **4 Tbyte per day (generated inside the car, not transmitted entirely)**
- MNOs typically bill based on resources used (\$ / bit / s), but V2V traffic should be free
 - Alternative business model to be developed to justify investments

THE COMING FLOOD OF DATA IN AUTONOMOUS VEHICLES

RADAR
~10-100 KB
PER SECOND

SONAR
~10-100 KB
PER SECOND

GPS
~50KB
PER SECOND

CAMERAS
~20-40 MB
PER SECOND

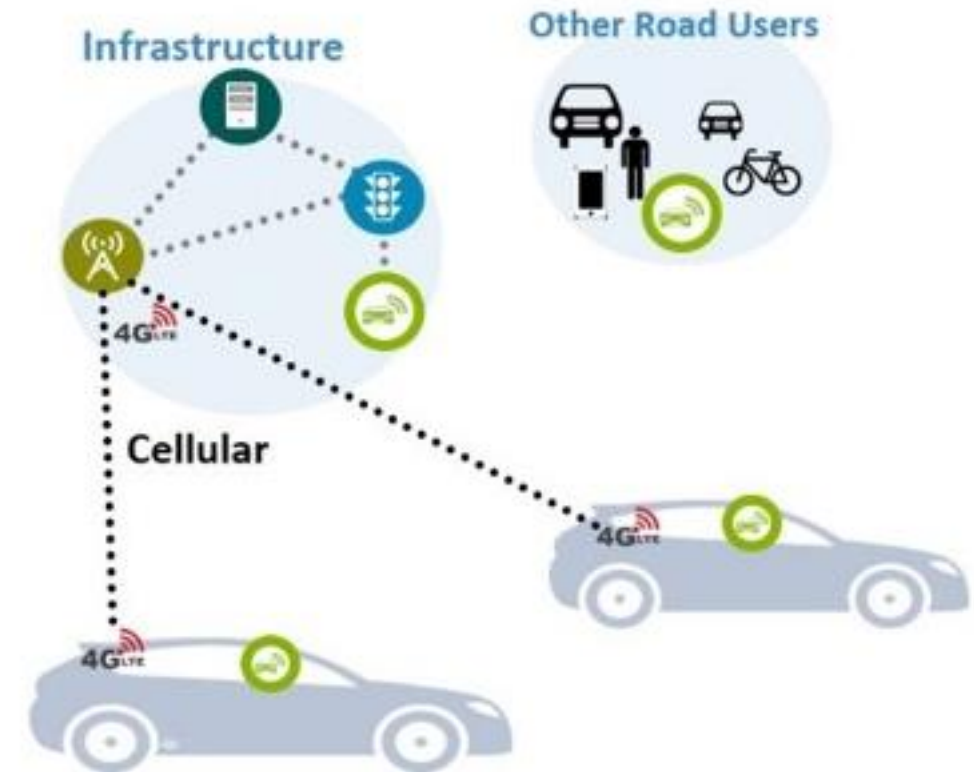
LIDAR
~10-70 MB
PER SECOND

AUTONOMOUS VEHICLES
4,000 GB
PER DAY... EACH DAY



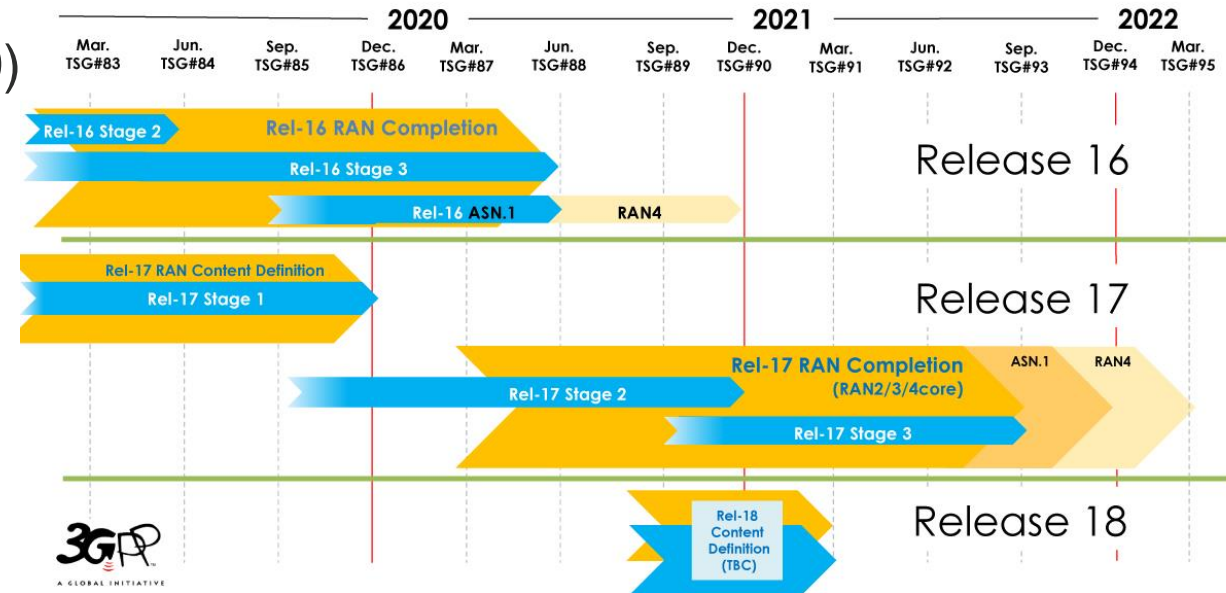
LTE support for V2x applications

- Some V2V use cases do not require high bandwidth, but **very low latency**
 - event-based broadcasting of Decentralized Environmental Notification messages (DENM) – e.g. fast braking
- Could work in the cellular network, but not always
 - Across multiple MNOs, across borders, across cells
- **Another solution: develop direct communication technology, as part of the cellular system**
 - **Device-to-Device** communication, part of Release 12, but not suitable for V2V
 - If two devices want to communicate directly, the network allocates the time / frequency resources
 - The network manages the interference generated by the D2D communication
 - Signalling/control via the eNodeB
 - Direct data sending between the UEs
 - D2D will not work if no continuous network coverage



C-V2x evolution

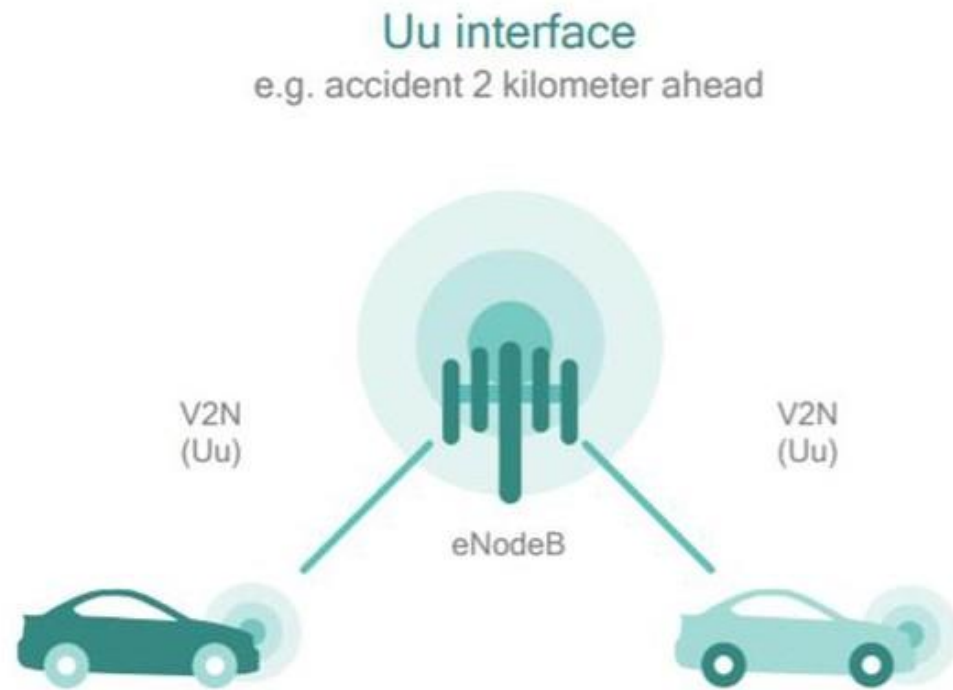
- LTE-D2D – Release 12 (2012)
- C-V2x Phase I – Release 14 (started in 2014, published in 2016)
 - V2V, V2I, V2N support
- C-V2x Phase II – Release 15 (published in 2018)
 - 5G support (called also 5G-V2x)
- C-V2x Phase III – Release 16 (expected for 2020)
 - Enhanced 5G support



C-V2X defines two complementary transmission modes

Network communications

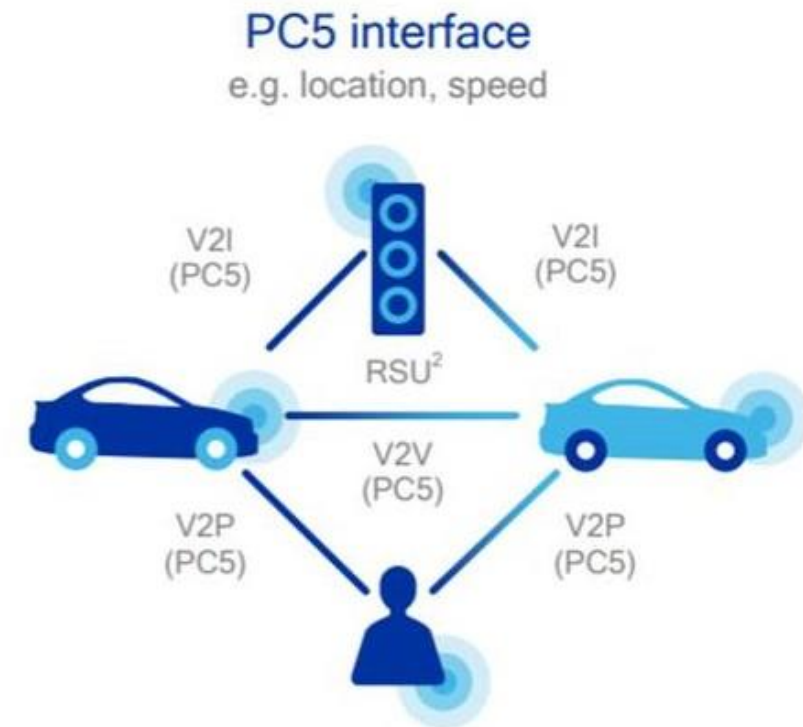
V2N on “Uu” interface operates in traditional mobile broadband licensed spectrum



On the traditional cellular spectrum

Direct communications

V2V, V2I, and V2P on “PC5” interface¹, operating in ITS bands (e.g. ITS 5.9 GHz) independent of cellular network



On 5,9 GHz

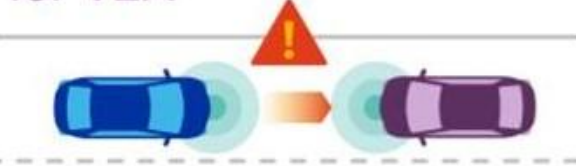
Continuous V2X technology evolution required

And careful spectrum planning to support this evolution

Evolution to 5G, while maintaining backward compatibility

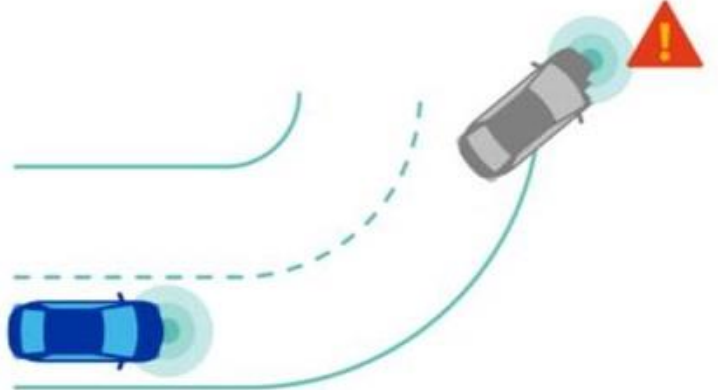
Basic safety 802.11p or C-V2X R14

Established foundation for V2X



Enhanced safety C-V2X R14/15

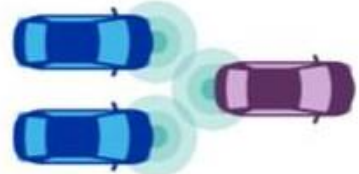
Enhanced range and reliability



Advanced safety C-V2X R16 (building upon R14)

Higher throughput
Higher reliability

Wideband ranging and positioning
Lower latency





5G

C-V2X

Rel 14/15 C-V2X
established basic safety

Rel 16 NR C-V2X saw
continued evolution for
advanced use cases

V2V
Vehicle-to-vehicle
e.g., collision avoidance safety systems

V2I
Vehicle-to-infrastructure
e.g., roadside traffic signal timing/priority

V2P
Vehicle-to-pedestrian
e.g., safety alerts to pedestrians, bicyclists

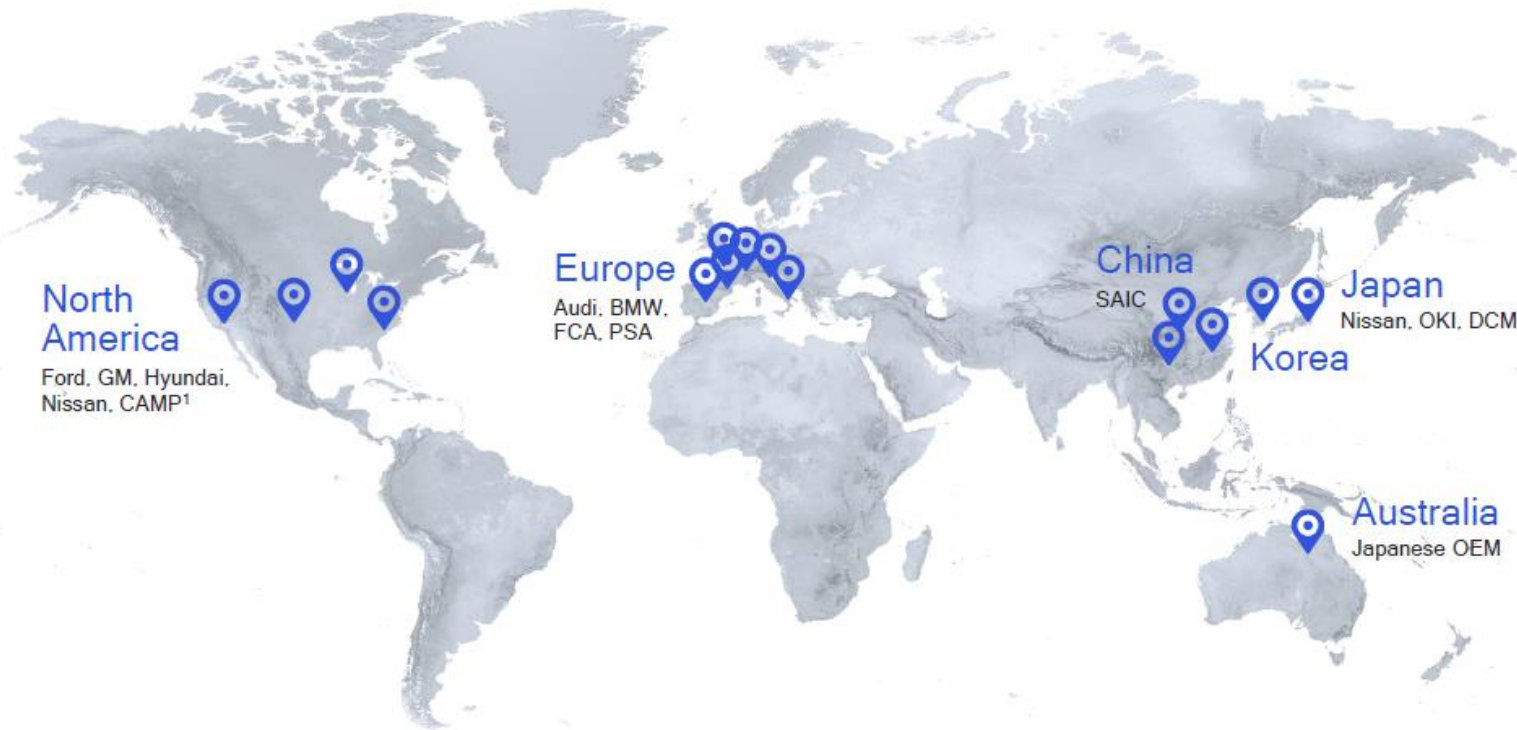
V2N
Vehicle-to-network
e.g., real-time traffic/routing, cloud services

- ✓ Release 14/15 C-V2X standards completed
- 5G Broad industry support with 5GAA
- 🌐 Global trials started in 2017; first commercial deployment expected in 2020
- 📍 Qualcomm® 9150 C-V2X chipset announced in September, 2017
- 🔄 Integration of C-V2X into the Qualcomm® Snapdragon™ Automotive 4G and 5G Platforms announced in February, 2019

Driving C-V2X global presence with trials and demos

Collaborating with key ecosystem players

CAMP	Ford	Quectel	Kapsch
PSA	Lear	SWARCO	Neusoft Reach
BMW	Valeo	Commsignia	Simcom
Daimler	WNC	Genvict	Sasken.
SAIC	CMCC	Nebulalink	Thundersoft
Continental	AT&T	R&S	Telit
Bosch	NTT DoCoMo	Datang	Lacroix
LG	CMRI	Ficosa	And more...
ZTE	McCain	Savari	



Gaining traction across numerous regions and industry sectors

From standards completion to independent field testing to initial deployments

5GAA Automotive Association

- 8 of the top 9 global automakers
- Top automotive Tier 1 suppliers
- 9 of the top 10 global telecommunications companies
- Top 3 global smartphone manufacturers
- Top global semiconductor companies
- Top 5 global wireless infrastructure companies
- Top global test and measurement companies and certification entities
- Global representation from Europe, China, US, Japan, Korea, and elsewhere

1. CAMP = Crash Avoidance Metrics Partnership LLC and this project includes the listed OEMs and Qualcomm.

Strong C-V2X momentum globally

